

Modelling HF Propagation

A TIGER Case Study

**Peter L. Dyson
Robert B. Norman
Murray L. Parkinson**

**Department of Physics
La Trobe University**

La Trobe  **Department
of Physics**



Outline

- 1. Ray Tracing**
- 2. Backscatter Ionograms**
- 3. TIGER Propagation in September 2000**
- 4. Conclusions**

Ray Equations – Hamilton/Haselgrove formulation

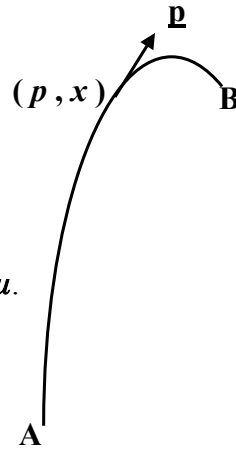
$$\frac{dx_i}{du} = p_i \quad \frac{dp_i}{du} = \frac{1}{2} \frac{\partial \mu^2}{\partial x_i}$$

where x_i , $i = 1, 2, 3$ is the coordinate of a point on the ray
 p_i , $i = 1, 2, 3$ is a vector in the wave normal direction with magnitude μ .
 μ is the refractive index

The phase path, P , given by $\frac{dP}{du} = \mu^2$

u is a parameter that varies monotonically along the ray path.

Usually $u = P'$, the group path.



Consider a ray tube

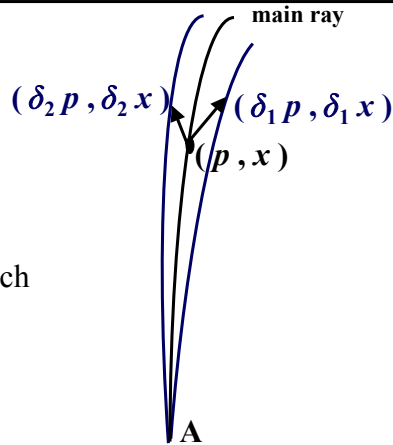
Rays adjacent to original ray can be considered perturbations of the original main ray.

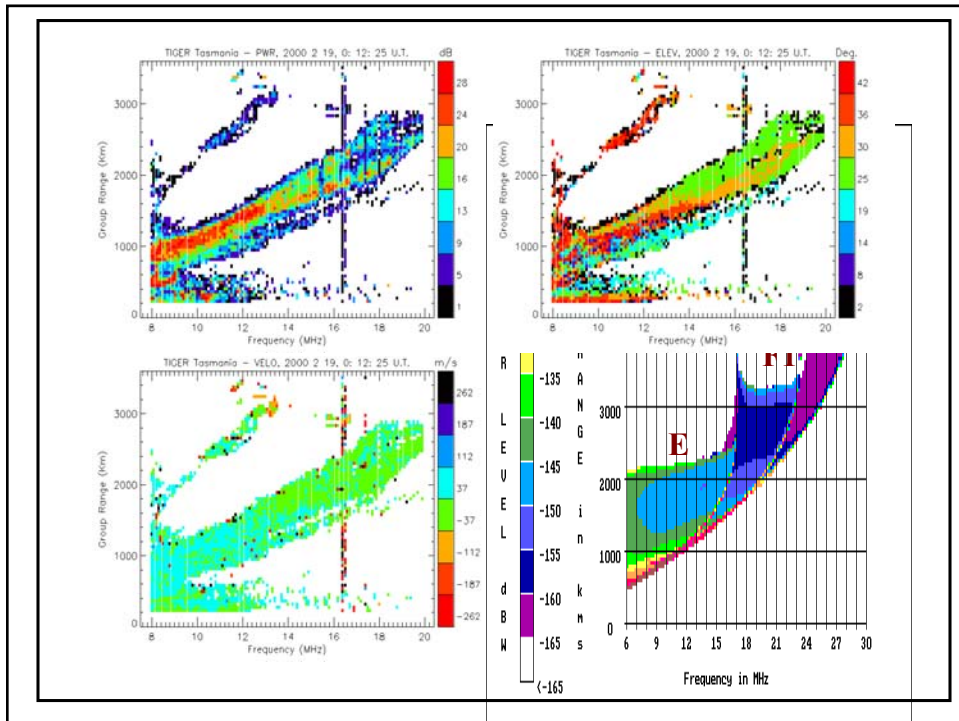
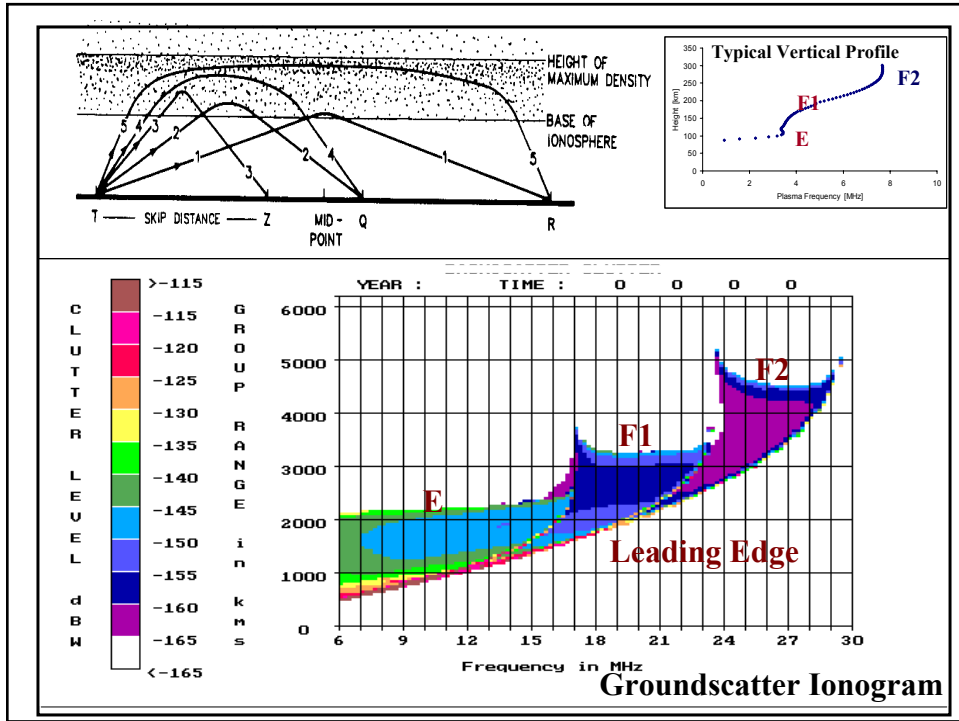
Using Hamilton's variational approach can show that

$$\frac{d}{du} (\delta_\beta x_i) = \delta_\beta p_i + p_i \frac{\partial \mu^2}{\partial x_j} \frac{\delta_\beta x_j}{\mu^2}$$

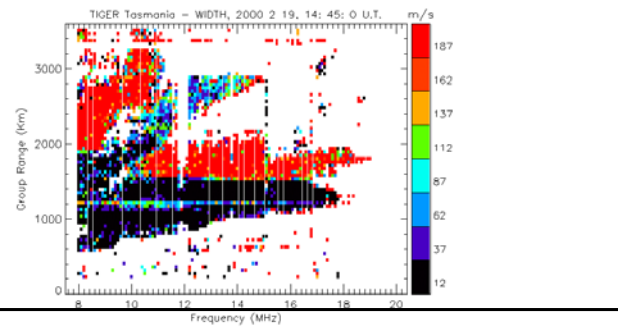
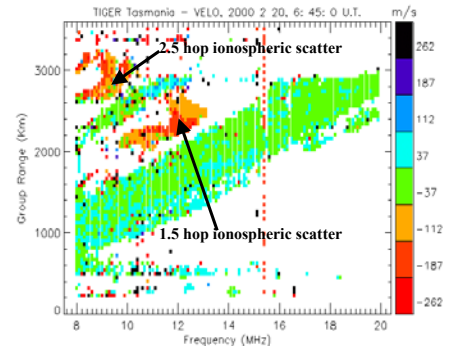
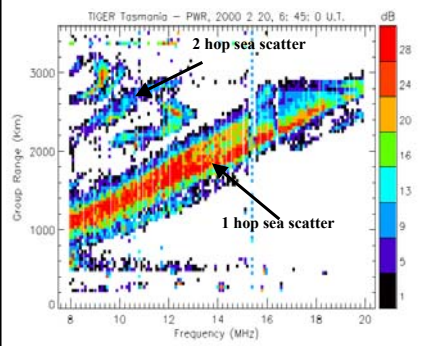
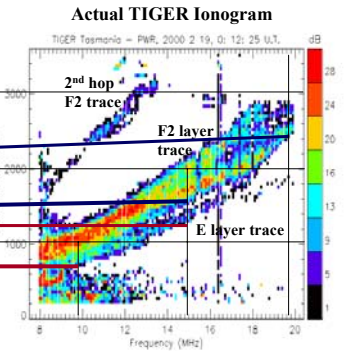
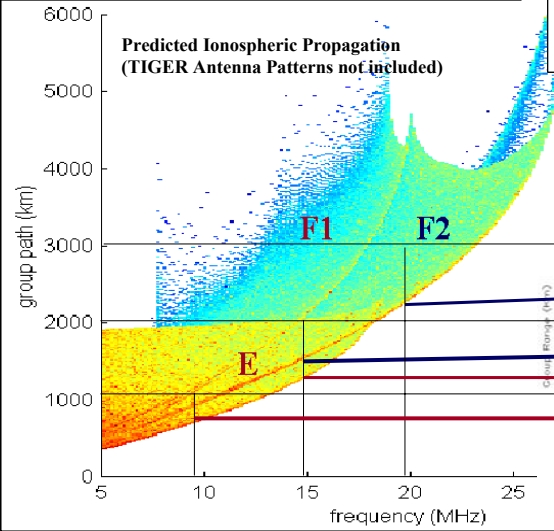
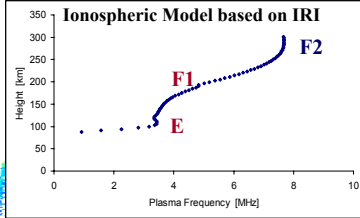
$$\frac{d}{du} (\delta_\beta p_i) = \frac{1}{2} \frac{\partial^2 \mu^2}{\partial x_i \partial x_j} \delta_\beta x_j - p_i \frac{1}{2\mu^2} \frac{\partial \mu^2}{\partial x_i} \frac{\partial \mu^2}{\partial x_j} \delta_\beta x_j \quad \beta = 1, 2$$

Power (ray divergence) at any point along ray is proportional to $(\delta_1 x \times \delta_2 x)$





Ray tracing simulation of a TIGER backscatter ionogram showing sea scatter echoes



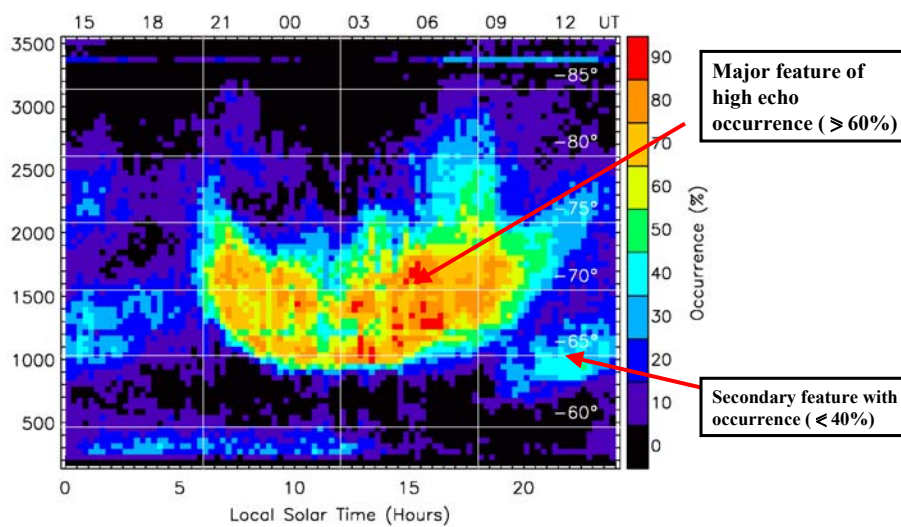
In normal SuperDARN operations a frequency at which significant scatter is occurring is automatically selected.

During Spring 2000 most common frequencies selected by TIGER were in the band 11.0 – 12.5 MHz.

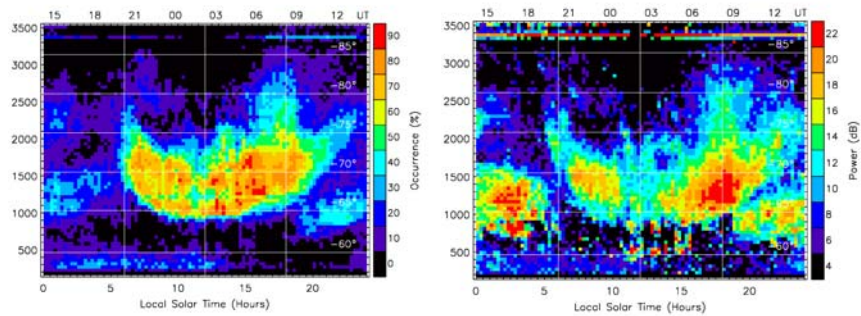
How do characteristics of sea scatter and ionospheric scatter observed at these frequencies compare with those predicted by IRI?

**IRI predictions based on 12 MHz
Tilted Dipole used to describe magnetic field**

**Sea echoes observed by TIGER during Spring of 2000
Percentage occurrence along Beam 4 for 11-12.5 MHz**



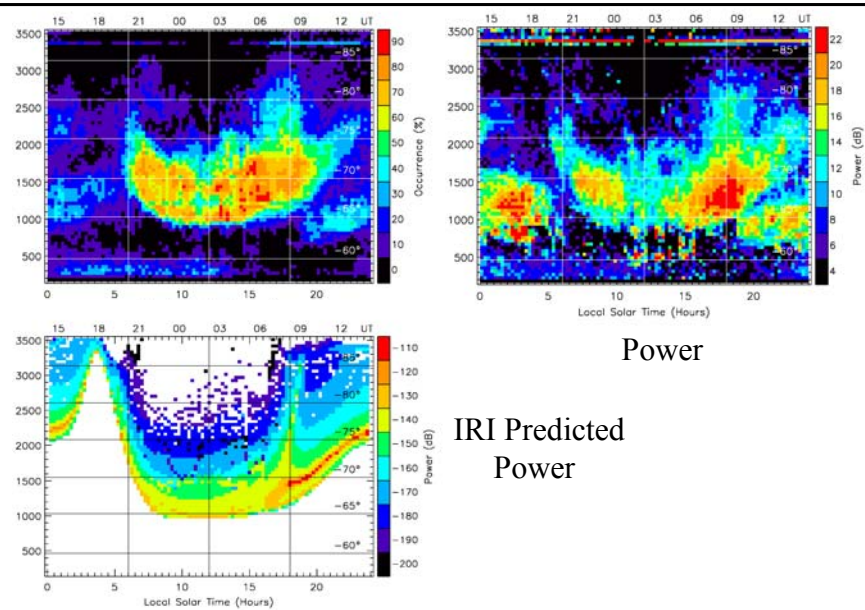
Sea echoes observed by TIGER during Spring of 2000 Percentage occurrence along Beam 4 for 11-12.5 MHz



Occurrence

Power

Comparison of IRI and Observations (Apples and Oranges)

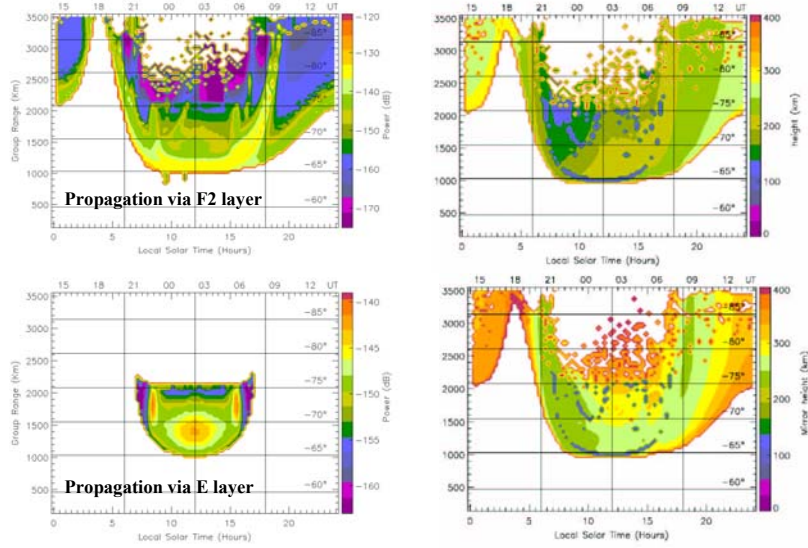


Power

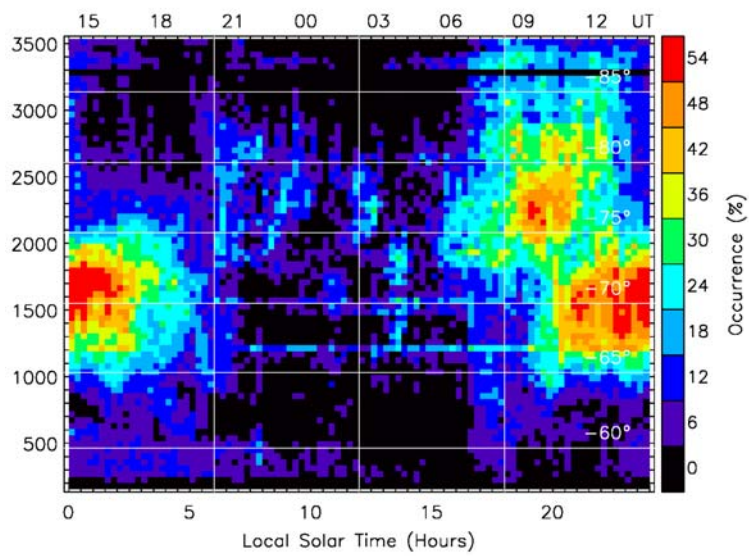
IRI Predicted
Power

Simulation using International Reference Ionosphere (IRI)

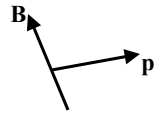
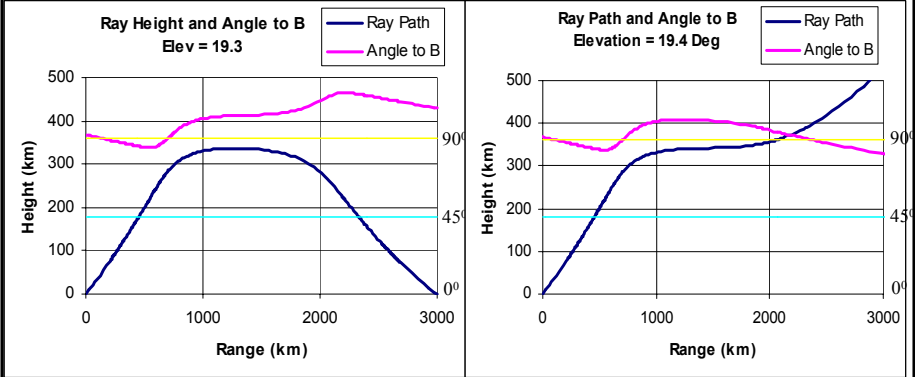
Relative Echo Strength at 12 MHz



Ionospheric Scatter Occurrence

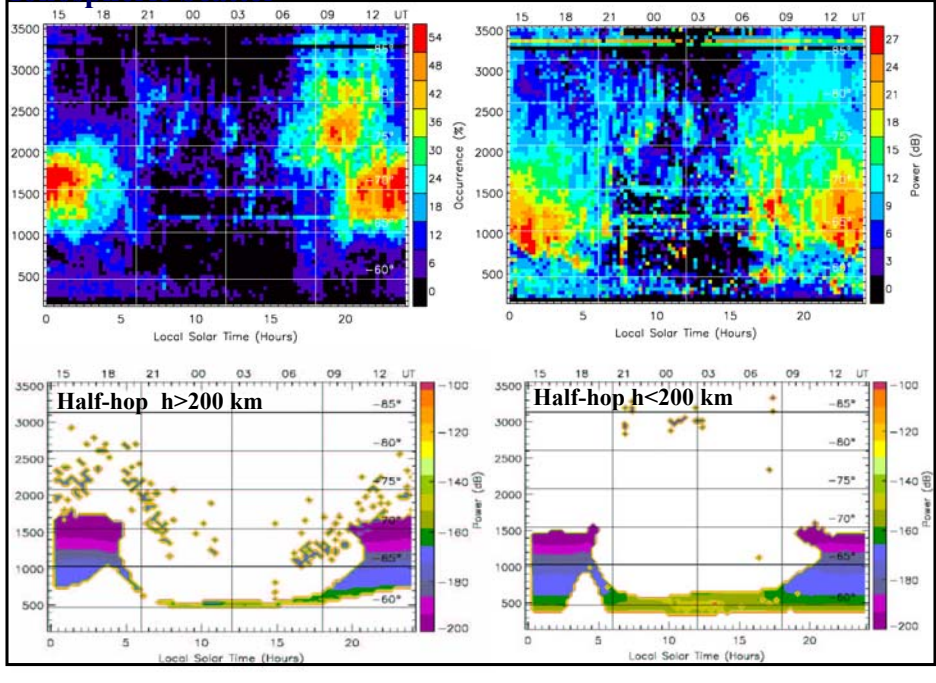


**Ionospheric Scatter:
can occur at normal incidence to field lines**

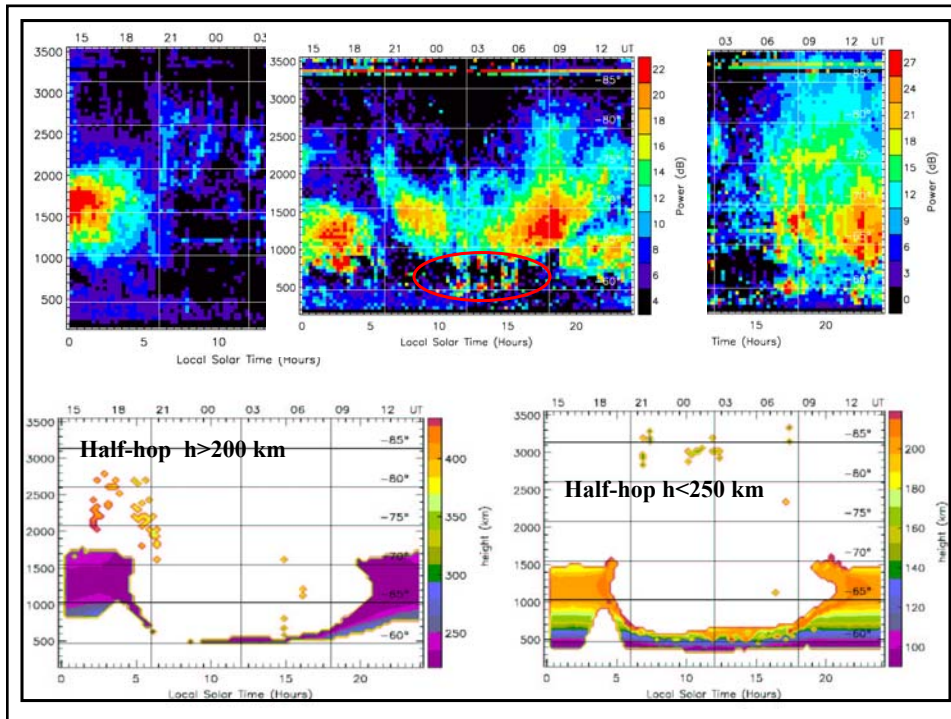
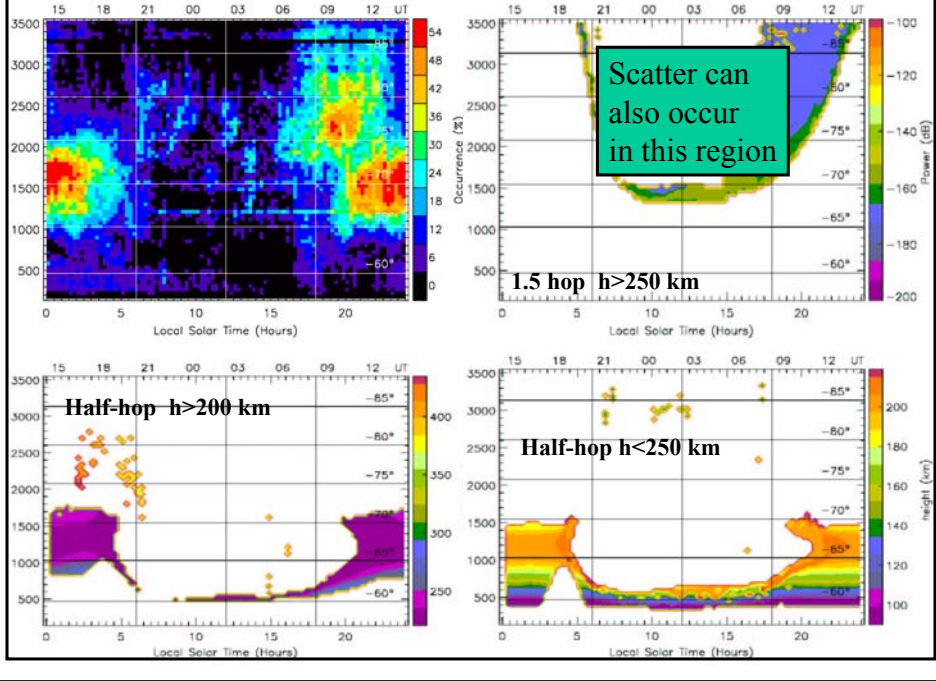


Since $\mathbf{B} \cdot \mathbf{p} = 0$ at more than one location along ray will consider two height regimes: above and below 200 km

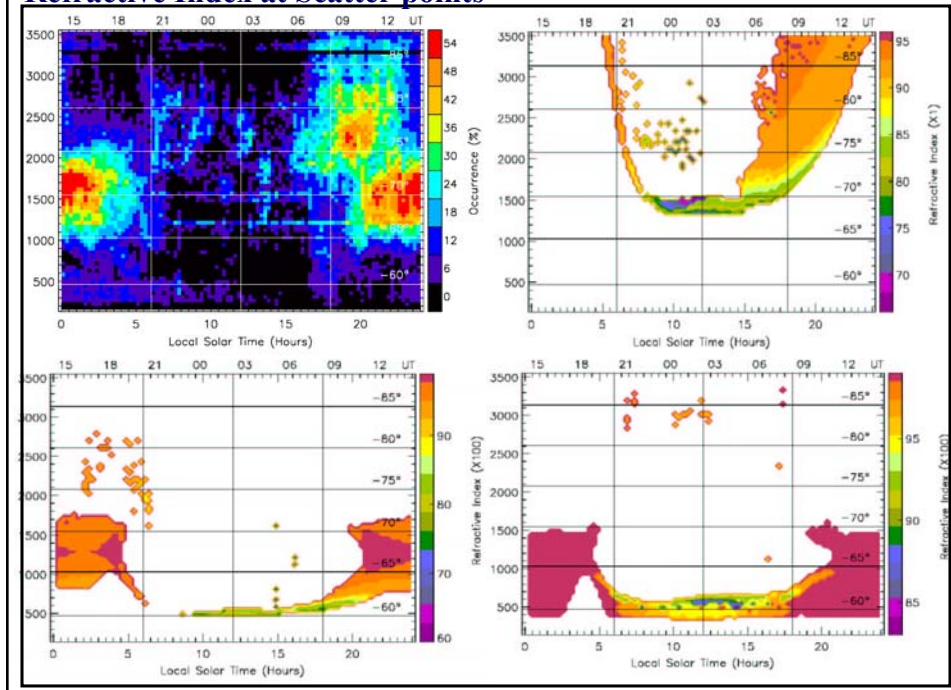
Ionospheric Scatter



Ionospheric Scatter



Refractive Index at Scatter points

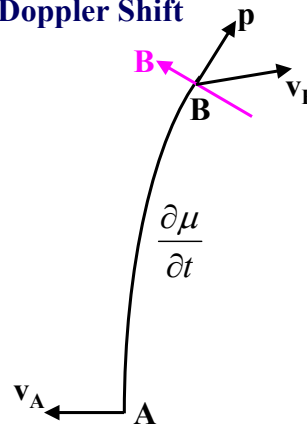


Effect of Background Ionosphere on Doppler Shift

$$P = \int_A^B \mu \cos \alpha \, ds$$

$$\frac{dP}{dt} = \int_A^B \frac{\partial \mu}{\partial t} \cos \alpha \, ds + [\mathbf{p} \cdot \mathbf{v}]_A^B$$

$$\Delta f = -\frac{f}{c} \frac{dP}{dt}$$



If time variation of phase path due only to reflection/scatter point

$$\Delta f = -\frac{f}{c} \mu_B v_{Blos} \quad v_{Blos} = \frac{1}{\mu_B} \frac{c}{f} \Delta f$$

Conclusions

For period considered (Spring 2000):

A. Sea-Scatter

- Location of daytime sea scatter predicted by IRI
- Echo power variations similar to IRI variations in ionospheric focussing
- Night-time echoes identified as sea-scatter not predicted by IRI

B. Ionospheric Scatter

- Ionospheric scatter occurs largely in regions where IRI predicts 0.5 and 1.5 hop scatter
- Night-time echoes identified as sea-scatter also occur where IRI predicts 0.5 hop scatter
- Scatter occurs in regions where $\mu > 0.9$, so scatter irregularity wavelength no greater than 10% larger than free space half-wavelength (12.5 m) and irregularity velocity no greater than 10% larger than “free space” value.

Acknowledgements

The TIGER program is funded by:

Australian Research Council
Australian Antarctic Science Program
Victorian Partnership for Advanced Computing
TIGER Consortium Partners